James-Michael Leahy

Department of Mathematics at Imperial College London and Applied Mathematics at University of Twente

Joint with Dan Crisan, Darryl Holm, and Torstein Nilssen

March 11th, 2021 CIRM: Pathwise Stochastic Analysis and Applications

Introduction and overview

- Rough path theory offers an attractive framework to model the effects of computationally unresolvable fluctuations on the resolvable parts of fluid flows. [Palmer et al., 2009].
- In [Leahy et al., 2020] we formulated geometric fluid dynamics on rough diffeomorphisms and characterized solutions of rough fluid PDEs as critical points of constrained action functionals.
- In [Leahy et al., 2021], we establish local well-posedness and a blow-up criterion for perfect incompressible fluids on geometric rough paths within the framework of unbounded rough drivers [Bailleul and Gubinelli, 2017].

Hamilton's principle: The Euler-Lagrange equations

- Let *Q* be a manifold and $L \in C^1(TQ, \mathbb{R})$.
- For given $q_1, q_2 \in Q$ and an interval $[t_1, t_2]$, define

$$C(q_1,q_2,[t_1,t_2]) = \left\{ q \in C^2([t_1,t_2];Q) : q(t_1) = q_1, \ q(t_2) = q_2 \right\}.$$

Theorem

A curve $q \in C(q_1, q_2, [t_1, t_2])$ is a critical point of

$$S(q) = \int_{t_1}^{t_2} L(q(t), \dot{q}(t)) \, \mathrm{d}t$$

if and only if

$$\frac{\mathrm{d}}{\mathrm{d}t}\left[\frac{\partial L}{\partial \dot{q}}(q,\dot{q})\right] = \frac{\partial L}{\partial q}(q,\dot{q}).$$

Hamilton-Pontryagin principle

- Let (q, v, p) be the local coordinates for the bundle $E := TQ \oplus T^*Q$.
- $C_E(q_1, q_2, [t_1, t_2]) :=$ $\{(q, v, p) \in C^1([t_1, t_2]; E) : q(t_1) = q_1, q(t_2) = q_2\}.$

Theorem ([Yoshimura and Marsden, 2006])

A curve $(q, v, p) \in C_E(q_1, q_2, [t_1, t_2])$ is a critical point of

$$S(q, v, p) = \int_{t_1}^{t_2} \left(L(q(t), u(t)) + p(t) \cdot (\dot{q}(t) - v(t)) \right) dt$$

if and only if

$$\dot{q} = v, \quad \dot{p} = \frac{\partial L}{\partial q}, \quad p = \frac{\partial L}{\partial v} \quad \Rightarrow \quad \frac{\mathrm{d}}{\mathrm{d}t} \frac{\partial L}{\partial \dot{q}} = \frac{\partial L}{\partial q}.$$

Lie group setting

- Let Q = G be a Lie group with Lie algebra $\mathfrak{g} = T_e G \cong \mathfrak{X}_R(G)$.
- Assume that the Lagrangian $L \in C^1(TG; \mathbb{R})$ is right-invariant so that

$$\int_{t_1}^{t_2} L(q(t), \dot{q}(t)) \, \mathrm{d} = \int_{t_1}^{t_2} \ell(u(t)) \, \mathrm{d}t, \quad u := TR_{q^{-1}} \dot{q} = \dot{q}q^{-1} : [t_1, t_2] \to \mathfrak{g},$$

where $\ell : \mathfrak{g} \to \mathbb{R}$ is defined by $\ell(u) := L(e, u), \ u \in \mathfrak{g}$.

• Assume the functional derivative $\frac{\delta \ell}{\delta u}$: $g \to g^*$ defined by

$$\frac{\mathrm{d}}{\mathrm{d}\epsilon}\Big|_{\epsilon=0}\ell(u+\epsilon\delta u) = \langle \frac{\delta\ell}{\delta u}(u), \delta u \rangle_{\mathfrak{g}}, \quad \forall \ \delta u \in \mathfrak{g}.$$

is a diffeomorphism.

• Recall that $ad = T_e Ad = T_e TL_g \circ TR_{g^{-1}} : \mathfrak{g} \to Der(\mathfrak{g})$ is given by

$$\operatorname{ad}_{\xi} u = -[u, \xi], \quad \forall \xi, u \in \mathfrak{g}.$$

• Let $\operatorname{ad}^* : \mathfrak{g} \to \operatorname{Der}(\mathfrak{g}^*)$ denote its dual relative to the pairing $\langle \cdot, \cdot \rangle_{\mathfrak{g}}$.

Euler-Poincaré reduction

- Let (q, u, λ) be the local coordinates for the bundle $E := G \times \mathfrak{g} \oplus \mathfrak{g}^*$.
- $C_E(q_1, q_2, [t_1, t_2]) :=$ { $(q, u, λ) ∈ C^1([t_1, t_2]; E) : q(t_1) = q_1, q(t_2) = q_2$ }.

Theorem ([Yoshimura and Marsden, 2007])

The following are equivalent for a curve $q \in C(q_1, q_2, [t_1, t_2])$ *:*

- q is a critical point of $S(q) = \int_{t_1}^{t_2} L(q(t), \dot{q}(t)) dt$.
- *q* satisfies the Euler-Lagrange equations.
- $(q, u = \dot{q}q^{-1}, \lambda = \frac{\delta\ell}{\delta u}) \in C_E(q_1, q_2, [t_1, t_2])$ is a critical point of $S(q, u, \lambda) = \int_{t_1}^{t_2} \ell(u(t)) + \langle \lambda(t), \dot{q}(t)q^{-1}(t) - u(t) \rangle_g.$

• $u = \dot{q}q^{-1} \in g$ satisfies the Euler-Poincaré equations [Holm et al., 1998]

$$\frac{\mathrm{d}}{\mathrm{d}t}\frac{\delta\ell}{\delta u} + \mathrm{ad}_u^* \frac{\delta\ell}{\delta u} = 0.$$

Topological ideal hydrodynamics [Arnold, 1966]

- Let $G = \text{Diff}_{\mu_g}^s(M)$, $s > \frac{d}{2} + 1$, be the topological group of Sobolev volume-preserving diffeomorphisms on (M, g).
- $g := T_e G \cong \mathfrak{X}^s_{\mu_g}(M)$ is isomorphic to the space of divergence-free Sobolev vector fields.
- Define for $q \in C(q_1, q_2, [0, T])$ with $u = \dot{q}q^{-1} : [0, T] \rightarrow \mathfrak{X}^s_{\mu_g}(M)$:

$$S(q) = \int_0^T \int_M g_{q_t} \left(\dot{q}_t, \dot{q}_t \right) \mu_g \, \mathrm{d}t = \int_0^T \int_M |u|^2 \mu_g \, \mathrm{d}t.$$

• There exists a smooth geodesic spray [Ebin and Marsden, 1970]:

 $\nabla_{\dot{q}}\dot{q} = -\nabla p \circ q$, Euler-Lagrange equations,

 $\Leftrightarrow \quad \partial_t u + \nabla_u u = -\nabla p$, Euler-Poincare equations,

where ∇ is the Levi-Civita connection on Diff^s(*M*) induced by the 'weak' energy metric.

Co-adjoint operator on diffeomorphism group

- Until further specified, all quantities are smooth.
- Let G = Diff(M) and $g = \mathfrak{X}(M) = \mathfrak{X}$.
- The canonical dual is given by $\mathfrak{g}^* = \mathfrak{X}^{\vee} = \Omega^1 \otimes \Omega^d$ with pairing

$$\langle \alpha \otimes \mu, u \rangle_{\mathfrak{X}} = \int_{M} \alpha(u) \mu, \quad \alpha \otimes \mu \in \mathfrak{X}^{\vee}, \ u \in \mathfrak{X}.$$

- Similarly, we can take volume-preserving *G* = Diff_{µg} and g = 𝔅_{µg} with the corresponding 𝔅[∨]_{µg} using the Hodge decomposition.
- We have $\operatorname{ad}_{u} v = -[u, v] = -\pounds_{u} v$ for all $u, v \in \mathfrak{X}$.
- Integrating by parts, we find [Holm et al., 1998]

$$\langle \alpha \otimes \mu, \operatorname{ad}_{u} v \rangle_{\mathfrak{X}} = \langle \pounds_{u}(\alpha \otimes \mu), v \rangle_{\mathfrak{X}},$$

and thus the co-adjoint operator is the Lie derivative

$$\operatorname{ad}_{u}^{*} = \pounds_{u} : \mathfrak{g}^{*} \to \operatorname{Der}(\mathfrak{g}^{*}).$$

Advected quantities and the Lagrangian

- $\circ~$ Let ${\mathfrak A}$ be a summand of tensor field bundles.
- Paths in A are advected quantities such as temperature and density.
- Denote the corresponding duality pairing by $\langle \cdot, \cdot \rangle_{\mathfrak{A}} : \mathfrak{A}^{\vee} \times \mathfrak{A} \to \mathbb{R}$.
- Define the momentum map $\diamond : \mathfrak{A}^{\vee} \times \mathfrak{A} \to \mathfrak{X}^{\vee}$ [Holm et al., 1998]:

$$\langle b, \pounds_u a \rangle_{\mathfrak{A}} = -\langle b \diamond a, u \rangle_{\mathfrak{X}} \quad \forall a \in \mathfrak{A}, \ b \in \mathfrak{A}^{\vee}, \ u \in \mathfrak{X}.$$

- Let $\ell : \mathfrak{X} \times \mathfrak{A} \to \mathbb{R}$ denote the fluid Lagrangian, which is physically determined.
- Assume that $\frac{\delta \ell}{\delta u} : \mathfrak{X} \times \mathfrak{A} \to \mathfrak{X}^{\vee}$ and $\frac{\delta \ell}{\delta a} : \mathfrak{X} \times \mathfrak{A} \to \mathfrak{A}^{\vee}$ are continuous:

$$\frac{\mathrm{d}}{\mathrm{d}\epsilon}\Big|_{\epsilon=0}\ell(u+\epsilon\delta u,a+\epsilon\delta a) = \langle \frac{\delta\ell}{\delta u}(u,a),\delta u\rangle_{\mathfrak{X}} + \langle \frac{\delta\ell}{\delta a}(u,a),\delta a\rangle_{\mathfrak{M}}$$

Geometric rough flows

- Let $K \in \mathbb{N}$, $\alpha \in (\frac{1}{3}, \frac{1}{2}]$, and $\mathbb{Z} \in \mathscr{C}_{g}^{\alpha}(\mathbb{R}_{+}; \mathbb{R}^{K})$ be an α truly rough geometric rough path.
- Let $\xi = (\xi_k)_{k=1}^K \in \mathfrak{X}^K$ be a collection of smooth vector fields.
- Let $\text{Diff}_{\mathbb{Z}}$ denote the space of rough flows $\{\eta_t\} \subset \text{Diff}$:

$$d\eta_t = v_t \circ \eta_t dt + \sigma_t \circ \eta_t d\mathbf{Z}_t, \quad \eta_0 = \mathrm{id},$$

for arbitrarily given $(v, \sigma) \in C^{\alpha}_{T}(\mathfrak{X}) \times C^{\infty}_{T}(\mathfrak{X}^{K})$.

• For a given controlled rough path $\lambda \in \mathfrak{D}_{Z,T}(\mathfrak{X}^{\vee})$, define

$$\int_0^T \langle \lambda_t, \mathrm{d}\eta_t \eta_t^{-1} \rangle_{\mathfrak{X}} := \int_0^T \langle \lambda_t, v_t \rangle_{\mathfrak{X}} \, \mathrm{d}t + \int_0^T \langle \lambda_t, \sigma_t \rangle_{\mathfrak{X}} \, \mathrm{d}\mathbf{Z}_t.$$

H-P variational principle on geometric rough paths

Theorem

A curve (η, u, λ) is a critical point of

$$S^{HP_{\mathbf{Z}}}(\eta, u, \lambda) = \int_0^T \ell(u_t, \eta_{t*}a_0) \mathrm{dt} + \langle \lambda_t, d\eta_t \eta_t^{-1} - u_t \mathrm{dt} - \xi \mathrm{d}\mathbf{Z}_t \rangle_{\mathfrak{X}}.$$

 $i\!f\!f(\eta, u, \lambda = \tfrac{\delta\ell}{\delta u}) \in \mathrm{Diff}_{\mathbf{Z}} \times C^{\alpha}_{T}(\mathfrak{X}) \times \mathfrak{D}_{Z,T}(\mathfrak{X}^{\vee}) \, satisfy$

$$d\eta_t = u_t \circ \eta_t dt + \xi \circ \eta_t d\mathbf{Z}_t, d\frac{\delta\ell}{\delta u} + \mathcal{L}_{u_t} \frac{\delta\ell}{\delta u} dt + \mathcal{L}_{\xi} \frac{\delta\ell}{\delta u} d\mathbf{Z}_t \stackrel{\mathfrak{X}^\vee}{=} \frac{\delta\ell}{\delta a} \diamond a_t dt.$$

By the rough Lie chain rule, $a_t = \eta_{t*}a_0$ *satisfies*

$$\mathrm{d}a + \pounds_{u_t} a \mathrm{d}t + \pounds_{\xi} a \mathrm{d}\mathbf{Z}_t \stackrel{\mathfrak{A}}{=} 0.$$

The density $D \in C^{\alpha}_T(\Omega^d)$ is an advected quantity:

$$\mathrm{d}D + \pounds_u D\mathrm{d}t + \pounds_\xi D\mathrm{d}\mathbf{Z}_t = 0 \quad \Leftrightarrow \quad D_t = \eta_{t*} D_0.$$

Theorem

Let Γ denote a compactly embedded one-dimensional smooth submanifold of *M*. If D_0 is non-vanishing, then

$$\int_{\eta_t \Gamma} \frac{1}{D_t} \frac{\delta \ell}{\delta u}(u_t, a_t) = \int_{\Gamma} \frac{1}{D_0} \frac{\delta \ell}{\delta u}(u_0, a_0) + \int_0^t \int_{\eta_s \Gamma} \frac{1}{D_s} \frac{\delta \ell}{\delta a}(u_s, a_s) \diamond a_s \mathrm{d}s.$$

Rough incompressible Euler system

- Let $\dot{\mathfrak{X}}_{\mu_g}$ denote the incompressible and 'harmonic-free' vector fields.
- Define the kinetic energy Lagrangian $\ell : \dot{\mathfrak{X}}_{\mu_g} \to \mathbb{R}$ by

$$\ell(u) = \frac{1}{2} \int_M g(u, u) \mu_g.$$

• Thus, $\frac{\delta \ell}{\delta u} = [u^{\flat} \otimes \mu_g] \in \mathfrak{X}_{\mu_g}^{\vee}$, which is an equivalence class.

• The corresponding equation for a critical point is given by:

$$\begin{cases} du^{\flat} + \pounds_{u} u dt + \pounds_{\xi} u^{\flat} d\mathbf{Z}_{t} = -\mathbf{d}(dq_{t} - 2^{-1}|u|^{2} dt) - dh_{t}^{\flat} \\ div_{\mu_{g}} u^{\flat} = 0, \quad H(u^{\flat}) = 0, \quad H(q) = 0, \\ u|_{t=0} = u_{0}, \end{cases}$$

where **d** denotes the exterior derivative, and the pressure term q and harmonic term h correspond to two constraints.

Since the exterior derivative **d** commutes with Lie derivatives, $\mathbf{d}^2 = 0$, and $\mathbf{d}h^{\flat} = 0$, we get that the vorticity $\omega = \mathbf{d}u^{\flat} \in \Omega_2$ is 'advected'

$$\begin{cases} d\omega + \mathcal{L}_u \omega dt + \mathcal{L}_{\xi} \omega d\mathbf{Z}_t = 0, \\ u = \sharp \mathbf{d}_g^{\star} \Delta^{-1} \omega =: \mathrm{BS}(\omega), \\ \omega|_{t=0} = \mathbf{d} u_0^{\mathrm{b}}. \end{cases}$$

In particular, the dynamics of the vorticity preserve exactness and thus there are no Lagrange multipliers, which is exploited in our proof of well-posedness.

Rough incompressible fluid on the torus

- Let $K \in \mathbb{N}$, $p \in [2,3]$, and $\mathbb{Z} = (Z, \mathbb{Z}) \in \mathscr{C}_g^{p-\text{var}}(\mathbb{R}_+, \mathbb{R}^K)$
- Let $d \in \{2, 3, \ldots\}$, $m \ge \lfloor \frac{d}{2} \rfloor + 2$, and $\xi \in W^{m+2,\infty}(\mathbb{T}^d, \mathbb{R}^{d \times K})$.
- For $\nu \ge 0$, consider a system of rough PDEs on $\mathbb{T}^d \times [0, T]$ given by

$$\begin{cases} du + u \cdot \nabla u dt + (\xi_k \cdot \nabla u + (\nabla \xi_k)u) dZ_t^k = v \Delta u - \nabla dq_t - dh_t, \\ div \, u = 0, \quad \int_{\mathbb{T}^d} u \, dV = 0, \quad \int_{\mathbb{T}^d} q \, dV = 0, \\ u|_{t=0} = u_0, \quad q|_{t=0} = 0, \quad h|_{t=0} = 0 \end{cases}$$
(1)

where $u : [0,T] \times \mathbb{T}^d \to \mathbb{R}^d$ is a divergence and mean-free vector field, $q : [0,T] \times \mathbb{T}^d \to \mathbb{R}$ is a mean-free time-integrated pressure, and $h : [0,T] \to \mathbb{R}^d$ is a time-integrated harmonic constant.

- The case $\nu > 0$ was studied in [Leahy et al., 2020]. The $\nu = 0$ (i.e., Euler) is a new result.
- Henceforth, denote $L_k \phi = \xi_k \cdot \nabla \phi + (\nabla \xi_k) \phi$.

Solution via Davie's expansion

- Let \dot{P} denote the projection onto mean and divergence-free vector fields. Recall that $\dot{P} + Q + H = id$, where Q and H denote the gradient and harmonic projection, respectively.
- Let Zⁿ = (Zⁿ, Zⁿ) be the canonical lift of a sequence of piecewise smooth paths converging to Z in the rough path topology.
- For a given $u_0 \in W^{m,2}_{\sigma}$, there exists a maximal solution $u^n \in C([0, T_{\max}); \dot{W}^{m,2}_{\sigma})$ to the system (1) with **Z** replaced by **Z**^{*n*}.
- It follows that (c.f., [Bailleul and Gubinelli, 2017])

$$\begin{split} \delta u_{st}^n + \int_s^t \dot{P}[u_r^n \cdot \nabla u_r^n - v \Delta u_r^n] dr &= -\int_s^t \dot{P}L_k u_r^n dZ_r^{n,k} \\ &= -\dot{P}L_k u_s^n Z_{st}^{n,k} + \dot{P}L_k \dot{P}L_l u_s \mathbb{Z}_{st}^{n,lk} + u_{st}^{n,P,\sharp}, \end{split}$$

where $u_{st}^{n,P,\sharp} \in C_2^{\frac{p}{3}-\text{var}}([0,T]; \dot{W}_{\sigma}^{m-3,2}).$

Definition of solution of velocity equation

Definition

A path

$$u \in L^{\infty}_T \dot{W}^{m,2}_{\sigma} \cap C_T \dot{W}^{m-3,2}_{\sigma}$$

is said to be a $W^{m,2}$ - solution of (1) on [0, *T*] if

$$u_{st}^{\dot{P},\natural} := \delta u_{st} + \int_{s}^{t} \dot{P}[u_{r} \cdot \nabla u_{r} - v \Delta u_{r}] dr + \dot{P}L_{k}u_{s}Z_{st}^{k} - \dot{P}L_{k}\dot{P}L_{l}u_{s}Z_{st}^{lk}$$

satisfies $u^{\dot{p},\natural} \in C_{2,T,\text{loc}}^{\frac{p}{3}-\text{var}} \dot{W}_{\sigma}^{m-3,2}$. We say u is a $W^{m,2}$ -solution of (1) on [0,T) if u is a solution on the interval $[0,T-\epsilon]$ for all $\epsilon > 0$.

Reconstruction of pressure and harmonic constant

Proposition

If u is a $W^{m,2}$ -solution of (1) on [0, T], then there exists unique paths $q \in C_T^{p-\text{var}} \dot{W}^{m-2,2}$ and $h \in C_T^{p-\text{var}} \mathbb{R}^d$ initiating from zero such that

$$u_{st}^{\natural} := \delta u_{st} + \int_{s}^{t} (u_{r} \cdot \nabla u_{r} - v \Delta u_{r}) dr + L_{k} u_{s} Z_{st}^{k}$$
$$- L_{k} L_{l} u_{s} \mathbb{Z}_{st}^{lk} + \nabla \delta q_{st} + \delta h_{st}$$

satisfies
$$u^{\natural} \in C_{2,T,\text{loc}}^{\frac{p}{3}-\text{var}}W^{m-3,2}$$
.

We construct *q* and *h* via the sewing lemma:

$$\nabla q_t := -\int_0^t Q u_r \cdot \nabla u_r \, dr - \int_0^t Q L_k u_r dZ_r^k$$
$$h_t := -\int_0^t \int_{\mathbb{T}^d} (\nabla \xi_k) u_t dV dZ_r^k.$$

Equivalent vorticity formulation

Let $\dot{W}^{2,m}_{d}$ denote the L^2 -Sobolev space of *m*-times weakly differentiable functions taking values in the space of anti-symmetric matrices that are mean-free and have vanishing exterior derivative.

Proposition

If u is a $W^{m,2}$ -solution of (1) on the interval [0,T], then

$$\Omega = \operatorname{curl} u = (\nabla - D)u \in L_T^{\infty} \dot{W}_{\mathbf{d}}^{m-1,2} \cap C_T \dot{W}_{\mathbf{d}}^{m-4,2}$$
$$\Omega^{\natural} = \operatorname{curl} u^{\dot{P},\natural} \in C_{2,T,\operatorname{loc}}^{\frac{p}{3} - \operatorname{var}} \dot{W}_{\mathbf{d}}^{m-4,2}$$

satisfy with $\mathbf{L}_{v}\Phi = v \cdot \nabla \Phi + (\nabla v)\Phi + \Phi(Dv)$,

$$\Omega_{st}^{\natural} = \delta\omega_{st} + \int_{s}^{t} (\mathbf{L}_{u_{r}}\Omega_{r} - \nu\Delta\Omega_{r}) \, dr + \mathbf{L}_{\xi_{k}}\Omega_{s}Z_{st}^{k} - \mathbf{L}_{\xi_{k}}\mathbf{L}_{\xi_{l}}\Omega_{s}\mathbb{Z}_{st}^{lk}, \quad (2)$$

Conversely, if there exists ω and ω^{\natural} such that (2) holds with $\omega_0 = \operatorname{curl} u_0$ and $u := BS \omega$, then u is a $W^{m,2}$ -solution of (1).

Existence and uniqueness

Theorem

There exists a constant $C = C(d, m, p, |\xi|_{W^{m+2,\infty}})$ such that for any time T_* satisfying

$$\exp\left(C(1+\varpi_{\mathbb{Z}}(0,T_*))\right)T_* < \frac{1}{1+|u_0|_{W^{m,2}}},$$

there exists a unique $W^{m,2}$ -solution

$$u \in C_{w,T_*} \dot{W}_{\sigma}^{m,2} \cap C_{T_*} \dot{W}_{\sigma}^{m-,2} \cap C_{T_*}^{p-\mathrm{var}} \dot{W}_{\sigma}^{m-1,2}$$

of (1) on the interval $[0, T_*]$. If $\xi \in W^{m+4,\infty}$, then $u \in C_{T_*} \dot{W}_{\sigma}^{m,2}$.

Theorem

The above solution can be uniquely extended to a maximal time interval

$$u \in C_w([0, T_{\max}); \dot{W}^{m,2}_{\sigma}) \cap C([0, T_{\max}); \dot{W}^{m-,2}_{\sigma}) \cap C^{p-\operatorname{var}}([0, T_{\max}); \dot{W}^{m-1,2}_{\sigma})$$

Moreover, if $T_{\max} < \infty$ *, then* $\limsup_{t \uparrow_{\max}} |u_t|_{W^{m,2}} = \infty$ *.*

Continuous dependence on data

Theorem

Assume that $\{(u_0^n, v^n, \xi^n, \mathbb{Z}^n\}) \in \dot{W}_{\sigma}^{m,2} \times [0, \infty) \times W^{m+2,\infty} \times C_g^{p-\text{var}}$ converges to $\{(u_0, v, \xi, \mathbb{Z}\}).$

Let $\{(u^n, T_{\max}^n)\}_{n=1}^{\infty}$ and (u, T_{\max})) denote the maximal solutions corresponding to the data $\{(u_0^n, v^n, \xi^n, \mathbb{Z}^n)\}$ and $(u_0, v, \xi, \mathbb{Z})$, respectively.

Then there exists an $N \in \mathbb{N}$ such that for all $n \ge N$, $T_{\max}^n > T_{\max}$. Moreover, $\{u^n\}_{n=N}^{\infty}$ converges to u in $C([0, T_{\max}); \dot{W}_{\sigma}^{m-2})$ and the weak-star topology of $L^{\infty}([0, T_{\max}); \dot{W}_{\sigma}^{m,2})$.

In particular, if $v^n \rightarrow 0$, then the $W^{m,2}$ -Navier-Stokes solution u^{v^n} solutions tend to the Euler solution u.

Theorem

Let u denote the unique maximal $W^{m,2}$ -solution of (1). There exists a positive constants $C_1 = C_1(d, m)$ and $C_2 = C_2(p, d, m, |\xi|_{W^{m+2,\infty}})$ such that for all $t \in [0, T_{max})$,

$$|u_t|_{W^{m,2}} \le C_1(1+|u_0|_{W^{m,2}}) \exp\left(C_2 \bar{\omega}_{\mathbb{Z}}(0,t) \exp\left(C_2 \int_0^t |\Omega_r|_{L^{\infty}} \, \mathrm{d}r\right)\right).$$

Moreover, if $T_{\max} < \infty$, then $\int_0^{T_{\max}} |\Omega_t|_{L^{\infty}} dt = \infty$.

Global well-posedness in 2*d*

Corollary

Let u denote the unique maximal $W^{m,2}$ -solution of (1) and $\Omega = \operatorname{curl} u$. Then for all $t \in [0, T_{\max})$,

$$|\Omega_t|_{L^{\infty}} = |\Omega_0|_{L^{\infty}}, \text{ if } \nu = 0, \quad |\Omega_t|_{L^{\infty}} \le |\Omega_0|_{L^{\infty}}, \text{ if } \nu > 0.$$
(3)

Thus, by the BKM blow-up criterion, there exists a unique $W^{m,2}$ -solution of (1) on $[0, \infty)$. Moreover, there exists positive constants $C_1 = C_1(m)$ and $C_2 = C_2(p, m, |\xi|_{W^{m+2,\infty}})$ such that for all $t \in \mathbb{R}_+$,

 $|u_t|_{W^{m,2}} \le C_1(1+|u_0|_{W^{m,2}}) \exp\left(C_2 \omega_{\mathbb{Z}}(0,t) \exp\left(C_2 t |\Omega_t|_{L^{\infty}}\right)\right).$

Various results such as Wong-Zakai approximation, Large deviation principle, and the existence of a random dynamical system are consequences.

- Obtain solution estimates using only the velocity formulation. The issue we face is the incompressibility constraint. In particular, changing the structure of the noise in the velocity in a zero-order way leads to difficulties due to the changed structure in the vorticity equation.
- Uniqueness in 2D for ω₀ ∈ L[∞]. Existence seems possible, but we don't have enough regularity at the level of vorticity to take the L²-norm of the difference of two solutions. In the deterministic case, one proves uniqueness via the velocity formulation [Yudovich, 1963, Majda et al., 2002]. Perhaps one can use a rough flow approach like in the stochastic setting [Brzeźniak et al., 2016].

Future outlook for applications

- Develop numerical schemes for rough PDEs
- Calibrate ξ for a cross-validated set of Gaussian rough paths (e.g. FBM with *H*) on a coarse-grid from direct numerical simulations of the underlying unperturbed fluid PDE.
- How can we update the parameters of the subgrid model with real observational data?
- DNS data ought to be good for initializing parameters and learning subgrid parameters. In the case of Lorenz 96, we can compare with rigorous homogenization results.

Arnold, V. I. (1966).

On the differential geometry of infinite-dimensional Lie groups and its application to the hydrodynamics of perfect fluids. In *Vladimir I. Arnold-Collected Works*, pages 33–69. Springer.

Bailleul, I. and Gubinelli, M. (2017).
 Unbounded rough drivers.
 In Annales de la Faculté des sciences de Toulouse: Mathématiques, volume 26, pages 795–830.

 Brzeźniak, Z., Flandoli, F., and Maurelli, M. (2016).
 Existence and uniqueness for stochastic 2d euler flows with bounded vorticity.

Archive for Rational Mechanics and Analysis, 221(1):107–142.

Deya, A., Gubinelli, M., Hofmanova, M., and Tindel, S. (2019). A priori estimates for rough PDEs with application to rough conservation laws.

Journal of Functional Analysis, 276(12):3577–3645.

25

Ebin, D. G. and Marsden, J. (1970).

Groups of diffeomorphisms and the motion of an incompressible fluid.

Annals of Mathematics, pages 102–163.

Holm, D. D., Marsden, J. E., and Ratiu, T. S. (1998).
 The Euler–Poincaré equations and semidirect products with applications to continuum theories.
 Advances in Mathematics, 137(1):1–81.

Majda, A. J., Bertozzi, A. L., and Ogawa, A. (2002). Vorticity and incompressible flow. cambridge texts in applied mathematics.

Appl. Mech. Rev., 55(4):B77-B78.



Palmer, T., Buizza, R., Doblas-Reyes, F., Jung, T., Leutbecher, M., Shutts, G., Steinheimer, M., and Weisheimer, A. (2009). Stochastic parametrization and model uncertainty. Yoshimura, H. and Marsden, J. E. (2006). Dirac structures in Lagrangian mechanics Part ii: Variational structures.

Journal of Geometry and Physics, 57(1):209–250.

- Yoshimura, H. and Marsden, J. E. (2007).
 Reduction of Dirac structures and the Hamilton-Pontryagin principle.
 Reports on Mathematical Physics, 60(3):381–426.
- Yudovich, V. I. (1963).

Non-stationary flows of an ideal incompressible fluid. *Zhurnal Vychislitel'noi Matematiki i Matematicheskoi Fiziki*, 3(6):1032–1066.

Unbounded rough drivers

- Let $(E_n)_{0 \le n \le 3}$ be a scale of Banach spaces possessing a smoothing $(J^{\eta})_{\eta \in (0,1)}$. Denote $E_{-n} = E_n^*$.
- Assume $L_k \in \mathcal{L}(E_{n+1}, E_n), n \in \{0, 2\}, L_k L_l \in \mathcal{L}(E_{n+2}, E_n), n \in \{0, 1\}.$
- Assume that $\mu : [0, T] \to E_{-1}$ satisfies $|\delta \mu_{st}|_{E_{-1}} \leq \varpi_{\mu}(s, t)$.
- Assume that $f \in C_T E_{-0}$ is such that for all $\phi \in E_3$,

$$\langle f_{st}^{\natural}, \phi \rangle := \langle \delta f_{st}, \phi \rangle + \langle \delta \mu_{st}, \phi \rangle + \langle f_{s}, (L_{k}^{*}\phi Z_{st}^{k} + L_{l}^{*}L_{k}^{*}\mathbb{Z}_{st}^{lk})\phi \rangle$$

satisfies
$$f^{\natural} \in C_{2,\varpi_Z,T,\text{loc}}^{\frac{p}{3}-\text{var}} E_{-3}$$
.

• There exist an L = L(p) > 0 such that for all $(s, t) \in \Delta_{[t_0,T]}$ with $\omega_{\mathbf{A}}(s, t) + \omega_{\mu}(s, t) \leq L$,

$$\begin{split} |f^{\natural}|_{\frac{p}{3}-\mathrm{var},[s,t],E_{-3}}^{\frac{p}{3}} &\leq C\left(\sup_{s\leq r\leq t}|f_{r}|_{-0}\varpi_{\mathbb{Z}}(s,t)^{\frac{3}{p}} + \varpi_{\mu}(s,t)\varpi_{\mathbb{Z}}(s,t)^{\frac{1}{p}}\right),\\ |f|_{p-\mathrm{var},[s,t],E_{-0}}^{p} &\leq C\left(\varpi_{\mu}(s,t) + \sup_{s\leq r\leq t}|f_{r}|_{-0}(\varpi_{\mu}(s,t)^{\frac{1}{p}} + \varpi_{\mathbb{Z}}(s,t)^{\frac{1}{p}})\right). \end{split}$$

Aspects of the proof

- We form the system of equations of the derivatives of ω up to order m-1, $(\omega^{(m-1)}, \omega^{(m-1),\natural})$, and obtain a priori estimates of $|\omega^{\natural}|_{\frac{p}{3}-\text{var},W^{m-4,2}}$ and $|\omega|_{p-\text{var},W^{m-2,2}}$ in terms of $\sup_{s \le r \le t} |\omega|_{W^{m-1,2}}$ using URD estimates.
- We form the system of equation for (ω^(m-1) ⊗ ω^(m-1), ω^{(m-1),⊗2,β}) and obtain a bound on ω^{(m-1),⊗2,β} using URD in the L[∞]-scale. We then apply the rough Gronwall lemma [Deya et al., 2019] and Bihari's inequality to obtain estimates of sup_{s≤r≤t} |ω|_{W^{m-1,2}}, thereby closing the a priori estimates.
- To prove uniqueness, we work with the vorticity formulation and develop the equation for the square.